

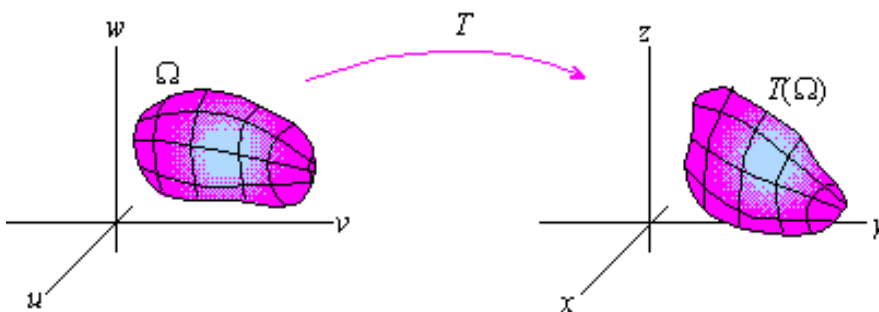
Curvilinear Coordinates

Cylindrical Coordinates

A 3-dimensional coordinate transformation is a mapping of the form

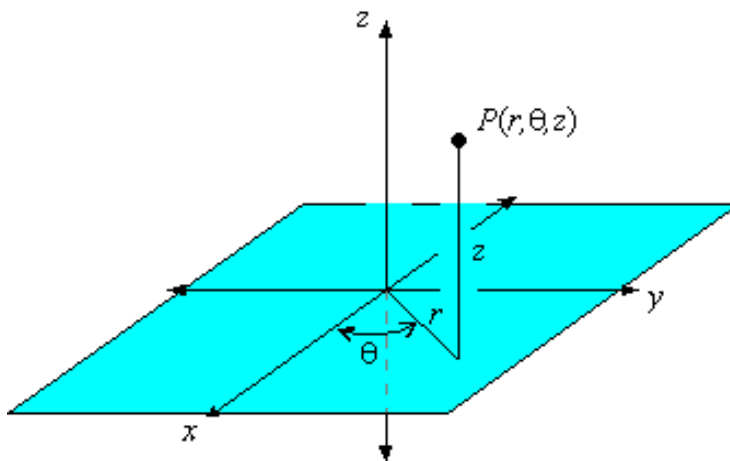
$$T(u, v, w) = \langle x(u, v, w), y(u, v, w), z(u, v, w) \rangle$$

Correspondingly, a 3-dimensional coordinate transformation T maps a solid Ω in the uvw -coordinate system to a solid $T(\Omega)$ in the xyz -coordinate system (and similarly, T maps curves in uvw to curves in xyz , surfaces in uvw to surfaces in xyz , and so on).



In this section, we introduce and explore two of the more important 3-dimensional coordinate transformations.

To begin with, the *cylindrical* coordinates of a point P are Cartesian coordinates in which the x and y coordinates have been transformed into polar coordinates (and the z -coordinate is left as is).



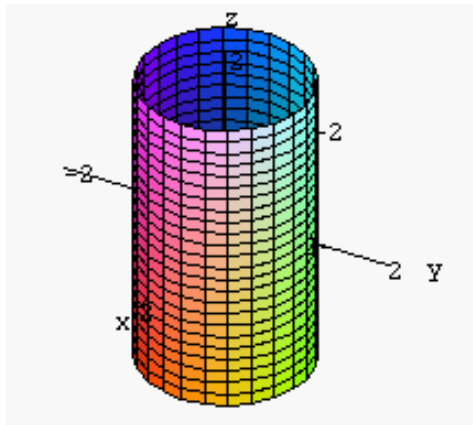
Not surprisingly, to convert to cylindrical coordinates, we simply apply $x = r \cos(\theta)$ and $y = r \sin(\theta)$ to the x and y coordinates. That is, the cylindrical coordinate transformation is

$$T(r, \theta, z) = \langle r \cos(\theta), r \sin(\theta), z \rangle$$

Cylindrical coordinates get their name from the fact that the surface " $r = \text{constant}$ " is a cylinder. For example, the cylinder

$$\mathbf{r}(\theta, z) = \langle \cos(\theta), \sin(\theta), z \rangle$$

is obtained by setting $r = 1$ in the cylindrical coordinate transformation.



Likewise, parameterizations of many other level surfaces can be derived from the cylindrical coordinate transformation.

In particular, if points in the xy -plane are in polar coordinates, then $z = f(r, \theta)$ is a *surface* in 3 dimensional space, and the parameterization of that surface is

$$\mathbf{r}(r, \theta) = \langle \cos(\theta), \sin(\theta), f(r, \theta) \rangle$$

More generally, $U(r, \theta, z) = k$ defines a *level surface* in which the xy components are represented in polar coordinates.

EXAMPLE 1 Find a parametrization of the right circular cone

$$z^2 = x^2 + y^2$$

by pulling back into cylindrical coordinates.

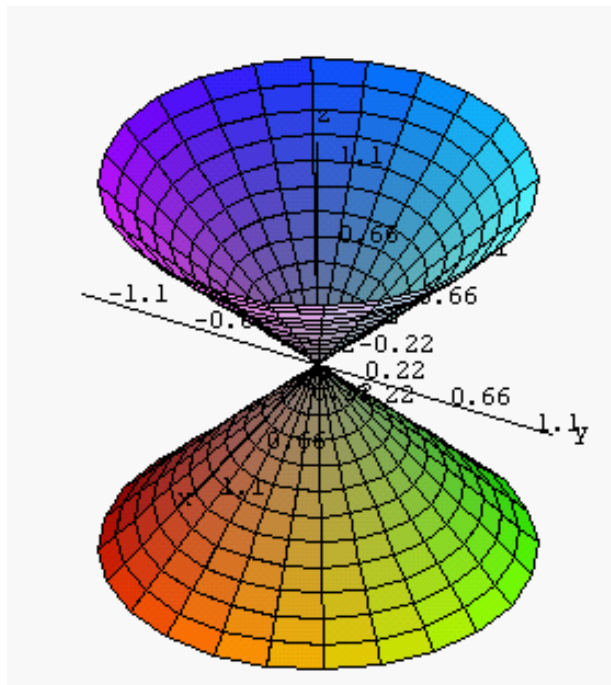
Solution: Transforming x and y into polar coordinates yields

$$z^2 = r^2, \quad z = r$$

Letting $z = r$ in the cylindrical coordinate transformation yields

$$\mathbf{r}(r, \theta) = \langle r \cos(\theta), r \sin(\theta), r \rangle$$

which is a parametrization of the right circular cone.



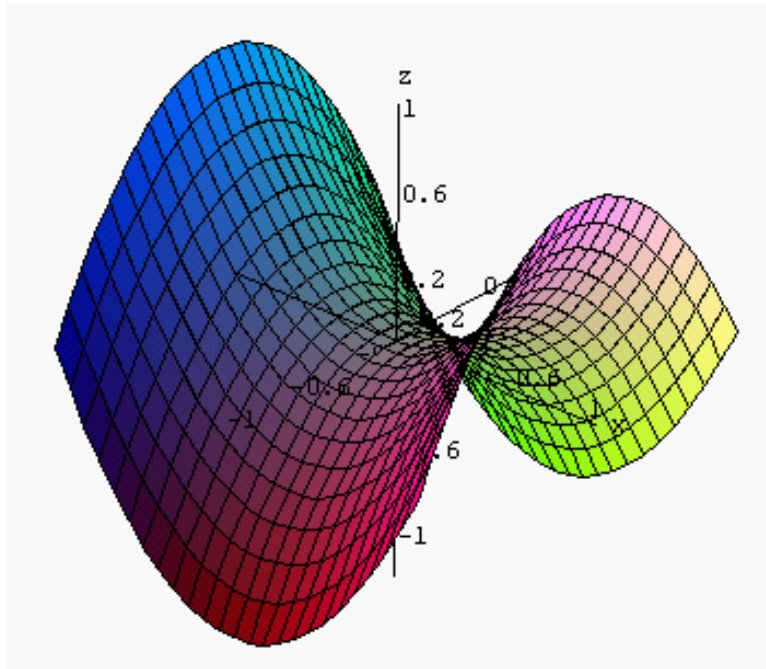
EXAMPLE 2 Parameterize the surface $z = x^2 - y^2$ by pulling back into cylindrical coordinates

Solution: Setting $x = r \cos(\theta)$ and $y = r \sin(\theta)$ leads to

$$z = r^2 \cos^2(\theta) - r^2 \sin^2(\theta) = r^2 \cos(2\theta)$$

Thus, the parametrization is

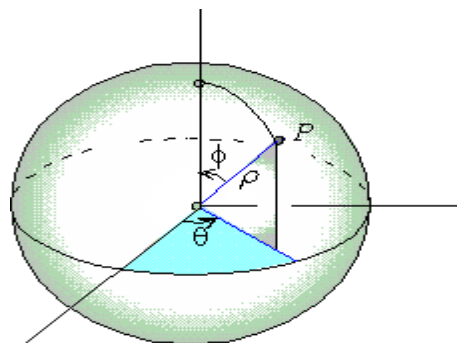
$$\mathbf{r}(r, \theta) = \langle r \cos(\theta), r \sin(\theta), r^2 \cos(2\theta) \rangle$$



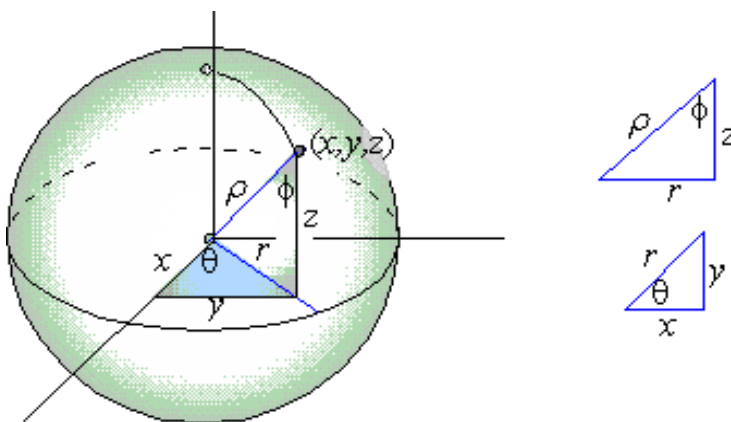
Check your Reading: In what plane are the cylindrical coordinates of a point the same as its polar coordinates?

Spherical Coordinates

The *spherical coordinates* of a point P are defined to be (ρ, ϕ, θ) , where ρ is the distance from P to the origin, ϕ is the angle formed by the z -axis and the ray from the origin to P , and θ is the angle from polar coordinates.



Specifically, the Cartesian coordinates (x, y, z) of a point P are related to the spherical coordinates (ρ, ϕ, θ) of P through two right triangles. Relationships among x, y, θ , and the polar distance r are contained in the familiar polar coordinate triangle. Relationships among r, z, ρ , and ϕ are conveyed by a second right triangle.



These 2 triangles are at the heart of spherical coordinates. For example, the triangle imply the relationships

$$\begin{aligned} x &= r \cos(\theta) & z &= \rho \cos(\phi) \\ y &= r \sin(\theta) & r &= \rho \sin(\phi) \end{aligned} \quad (1)$$

so that if we eliminate r using the fact that $r = \rho \sin(\phi)$, we obtain

$$x = \rho \sin(\phi) \cos(\theta), \quad y = \rho \sin(\phi) \sin(\theta), \quad z = \rho \cos(\phi) \quad (2)$$

which is the *coordinate transformation* that maps spherical coordinates into Cartesian coordinates.

EXAMPLE 3 Transform the point $(4, \pi/3, \pi/2)$ from spherical into Cartesian coordinates.

Solution: The transformation (2) implies that

$$\begin{aligned} x &= 4 \sin\left(\frac{\pi}{3}\right) \cos\left(\frac{\pi}{2}\right) = 4 \cdot \frac{\sqrt{3}}{2} \cdot 0 = 0 \\ y &= 4 \sin\left(\frac{\pi}{3}\right) \sin\left(\frac{\pi}{2}\right) = 4 \cdot \frac{\sqrt{3}}{2} \cdot 1 = 2\sqrt{3} \\ z &= 4 \cos\left(\frac{\pi}{3}\right) = 2 \end{aligned}$$

Thus, $(4, \pi/3, \pi/2)$ in spherical coordinates is the same point as $(0, 2\sqrt{3}, 2)$ in Cartesian coordinates.

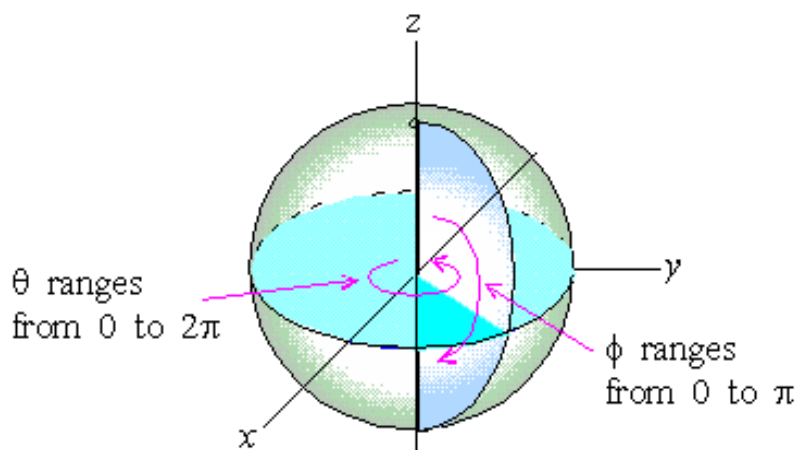
In spherical coordinates, $r = \rho \sin(\phi)$ and $z = \rho \cos(\phi)$, so that the polar equation $x^2 + y^2 = r^2$ becomes

$$x^2 + y^2 = \rho^2 \sin^2(\phi)$$

Moreover, $r^2 + z^2 = \rho^2$, so that we have the identity

$$x^2 + y^2 + z^2 = \rho^2 \tag{3}$$

Thus, if R is constant, then $\rho = R$ is a sphere of radius R centered at the origin. In addition, we usually restrict θ to $[0, 2\pi]$ and ϕ to $[0, \pi]$ so that the sphere is covered only once.

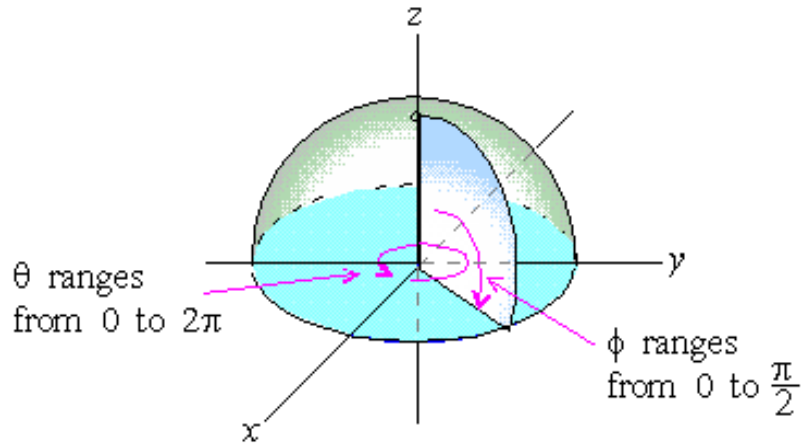


Restricting ϕ and θ to smaller intervals yields smaller sections of a sphere.

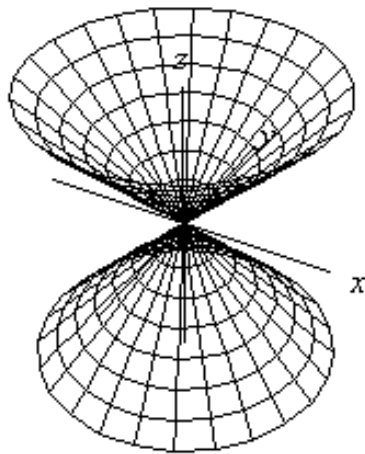
EXAMPLE 4 What section of the sphere $\rho = 1$ is given by ϕ in $[0, \pi/2]$, θ in $[0, 2\pi]$?

Solution: Since $\phi = \pi/2$ is the xy -plane, the set of points $\rho = 1$, ϕ in $[0, \pi/2]$, θ in $[0, 2\pi]$ is the part of the unit sphere above the

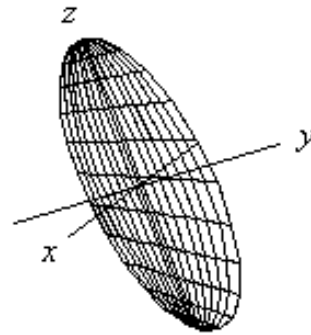
xy -plane—i.e., the upper hemisphere.



Similarly, $\phi = k$ for k constant is a cone with sides at angle k to the vertical, and $\theta = c$ for c constant is a vertical plane of the form $y = \tan(c)x$



$\phi = k$ for k constant



$\theta = c$ for c constant

Check your Reading: For what values of ϕ, θ is the *lower unit hemisphere* defined?

Surfaces in Spherical Coordinates

Since $x = \rho \sin(\phi) \cos(\theta)$, $y = \rho \sin(\phi) \sin(\theta)$, and $z = \rho \cos(\phi)$, the position vector of a point in space is

$$\mathbf{r}(\phi, \theta) = \langle \rho \sin(\phi) \cos(\theta), \rho \sin(\phi) \sin(\theta), \rho \cos(\phi) \rangle = \rho \mathbf{e}_\rho(\phi, \theta)$$

where we define $\mathbf{e}_\rho(\phi, \theta) = \langle \sin(\phi) \cos(\theta), \sin(\phi) \sin(\theta), \cos(\phi) \rangle$. That is, the surface $\mathbf{r}(\phi, \theta)$ can be written more compactly as

$$\mathbf{r}(\phi, \theta) = \rho \mathbf{e}_\rho(\phi, \theta)$$

It follows that the parameterization of the graph of $\rho = f(\phi, \theta)$ is given by

$$\mathbf{r}(\phi, \theta) = f(\phi, \theta) \langle \sin(\phi) \cos(\theta), \sin(\phi) \sin(\theta), \cos(\phi) \rangle \quad (4)$$

or equivalently, $\mathbf{r}(\phi, \theta) = f(\phi, \theta) \mathbf{e}_\rho(\phi, \theta)$

In particular, if we substitute $x = \rho \sin(\phi) \cos(\theta)$, $y = \rho \sin(\phi) \sin(\theta)$, and $z = \rho \cos(\phi)$ into the equation of a level surface and *solve for* ρ , then (4) parameterizes a *coordinate patch* on that level surface.

EXAMPLE 5 Pull back into spherical coordinates to obtain a parameterization of the hyperboloid in two sheets

$$z^2 - x^2 - y^2 = 1$$

Solution: Substituting from (2) and simplifying yields

$$\begin{aligned} \rho^2 \cos^2(\phi) - \rho^2 \sin^2(\phi) \cos^2(\theta) - \rho^2 \sin^2(\phi) \sin^2(\theta) &= 1 \\ \rho^2 \cos^2(\phi) - \rho^2 \sin^2(\phi) [\cos^2(\theta) + \sin^2(\theta)] &= 1 \\ \rho^2 \cos^2(\phi) - \rho^2 \sin^2(\phi) &= 1 \end{aligned}$$

However, $\cos^2(\phi) - \sin^2(\phi) = \cos(2\phi)$, so that $\rho^2 \cos(2\phi) = 1$ and

$$\rho^2 = \sec(2\phi) \quad (5)$$

Thus, the upper sheet of the hyperboloid is parameterized by $\mathbf{r}(\phi, \theta) = [\sec(2\phi)]^{1/2} \mathbf{e}_\rho$, which yields

$$\mathbf{r}(\phi, \theta) = \sqrt{\sec(2\phi)} \langle \sin(\phi) \cos(\theta), \sin(\phi) \sin(\theta), \cos(\phi) \rangle$$

since $\mathbf{e}_\rho = \langle \sin(\phi) \cos(\theta), \sin(\phi) \sin(\theta), \cos(\phi) \rangle$.

Spherical coordinates provides us a straightforward means of defining certain types of surfaces of revolution. If $0 \leq \alpha \leq \pi$ and if $f(\phi) \geq 0$ on $[0, \alpha]$ does **not** depend on θ , then the surface $\rho = f(\phi)$ on $[0, \alpha]$ is the revolution of the curve

$$\mathbf{r}(\phi, 0) = \langle f(\phi) \sin(\phi), 0, f(\phi) \cos(\phi) \rangle, \quad \phi \text{ in } [0, \alpha]$$

in the xz -plane around the z -axis. Correspondingly, it has a parameterization of

$$\mathbf{r}(\phi, \theta) = f(\phi) \mathbf{e}_\rho(\phi, \theta)$$

If $\alpha = \pi$ and $f(\phi)$ is positive and continuous on $[0, \pi]$, then $\rho = f(\phi)$ is called a radially symmetric *deformation of the sphere*.

EXAMPLE 6 Discuss the graph of the surface

$$\rho = 5 + 0.1\phi \sin(7\phi), \quad \phi \text{ in } [0, \pi]$$

Solution: The parameterization is given by .

$$\mathbf{r}(\phi, \theta) = (5 + 0.1\phi \sin(7\phi)) \mathbf{e}_\rho(\phi, \theta)$$

which by definition of $\mathbf{e}_\rho(\phi, \theta)$ leads to

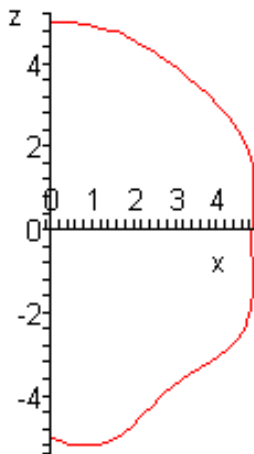
$$x = (5 + 0.1\phi \sin(7\phi)) \sin(\phi) \cos(\theta), \quad y = (5 + 0.1\phi \sin(7\phi)) \sin(\phi) \sin(\theta)$$

$$z = (5 + 0.1\phi \sin(7\phi)) \cos(\phi)$$

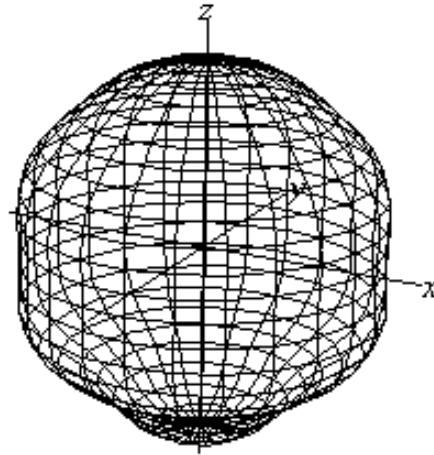
The surface is the revolution of the curve

$$\mathbf{r}(\phi, 0) = \langle (5 + 0.1\phi \sin(7\phi)) \sin(\phi), 0, (5 + 0.1\phi \sin(7\phi)) \cos(\phi) \rangle$$

about the z -axis. The curve is shown below:



The resulting surface of revolution then follows:



Check your Reading: Is the surface in example 6 a deformation of the sphere?

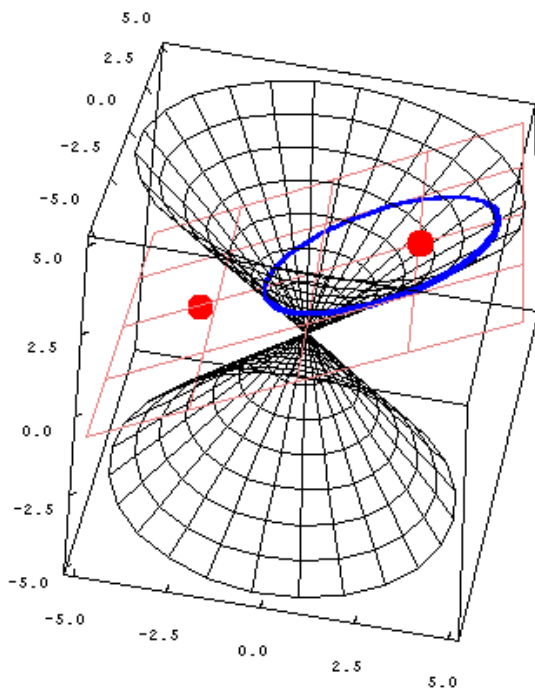
Conic Sections

A *conic section* is the curve formed by the intersection of a plane with the right circular cone $x^2 + y^2 = z^2$. For example, the plane in the conic explorer below is given by $z = p + \varepsilon x$, where p is the *parameter* of the conic and $\varepsilon > 0$ is its

eccentricity:

Parameter: $p = 1.98021$

Eccentricity: $\varepsilon = 0.55294$



If $\varepsilon = 0$, then the conic is a circle. If $0 < \varepsilon < 1$, then the conic is an ellipse. If $\varepsilon = 1$, then the conic is a parabola, and if $\varepsilon > 1$, then the conic is a hyperbola.

In cylindrical coordinates, the plane is given by $z = p + \varepsilon r \cos(\theta)$ and the cone is given by $r^2 = z^2$. As a result, the intersection of the plane and the cone is given by

$$\begin{aligned} r &= p + \varepsilon r \cos(\theta) \\ r - \varepsilon r \cos(\theta) &= p \\ r(1 - \varepsilon \cos(\theta)) &= p \end{aligned}$$

which results in

$$r = \frac{p}{1 - \varepsilon \cos(\theta)} \quad (6)$$

This is actually the graph of the projection in polar coordinates of the conic into the xy -plane.

projectino

Moreover, $z = \pm r$ and cylindrical coordinates implies that parameterization of the conic itself is

$$\boldsymbol{\rho}(\theta) = \left\langle \frac{p \cos(\theta)}{1 - \varepsilon \cos(\theta)}, \frac{p \sin(\theta)}{1 - \varepsilon \cos(\theta)}, \frac{p}{1 - \varepsilon \cos(\theta)} \right\rangle$$

where we use the vector-valued function $\boldsymbol{\rho}$ since its length is the spherical coordinate distance ρ .

EXAMPLE 7 Find the projection of the conic with eccentricity $\varepsilon = 1$ and parameter $p = 4$. What type of conic is it? What is the parameterization of the conic itself?

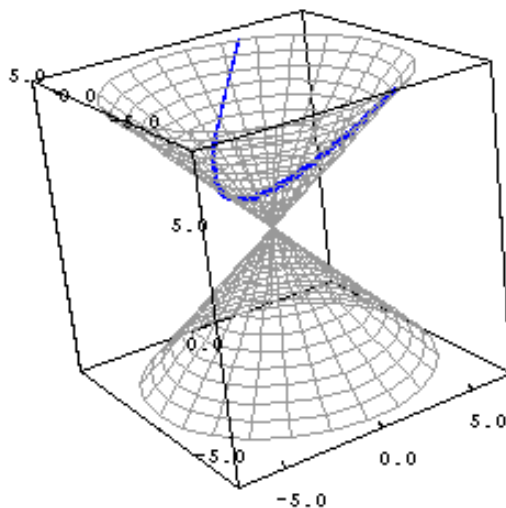
Solution: The projection is given by (6) with $\varepsilon = 1$ and $p = 4$:

$$r = \frac{4}{1 - \cos(\theta)}$$

This is a parabola with parameter $p = 4$. It is parameterized by

$$\boldsymbol{\rho}(t) = \left\langle \frac{4 \cos(\theta)}{1 - \cos(\theta)}, \frac{4 \sin(\theta)}{1 - \cos(\theta)}, \frac{4}{1 - \cos(\theta)} \right\rangle$$

which is shown below:



Conic projections of the form (6) are symmetric about the x -axis. Arbitrary conic projections follow from the intersection of the cone with an arbitrary plane, which is given by $z = ax + by + p$ with a , b , and p constant.

EXAMPLE 8 Find the projection of the conic formed by the intersection of $z = 3 + 0.5y$ with the right circular cone. What type of conic is it? What is the parameterization of the conic itself?

Solution: The intersection of $z = 3 + 0.5y$ with the right circular cone $r^2 = z^2$ is given by

$$r = 3 + 0.5r \sin(\theta) \quad \implies \quad r - r0.5 \sin(\theta) = 3$$

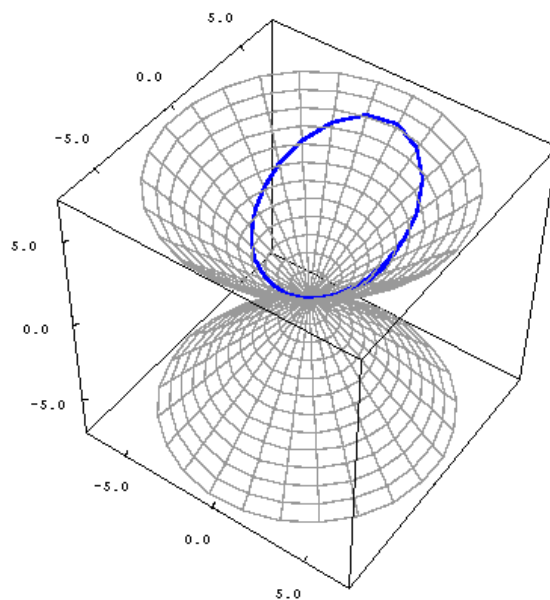
which results in the projection

$$r = \frac{3}{1 - 0.5 \sin(\theta)}$$

This is an ellipse with parameter $p = 3$ and eccentricity $\varepsilon = 0.5$ that is symmetric about the y -axis. Moreover, the conic itself has the parameterization

$$\boldsymbol{\rho}(\theta) = \left\langle \frac{3 \cos(\theta)}{1 - 0.5 \sin(\theta)}, \frac{3 \sin(\theta)}{1 - 0.5 \sin(\theta)}, \frac{3}{1 - 0.5 \sin(\theta)} \right\rangle$$

which is shown below:



Exercises

1. Convert the following points from cylindrical coordinates (r, θ, z) to Cartesian coordinates (i.e., xyz coordinates):

- a. $(3, \pi/3, 3)$ b. $(7, \pi/2, 0)$
c. $(5, 0, 0)$ d. $(4, \pi, -2)$

2. What section of the cylinder $x^2 + y^2 = 1$ corresponds to cylindrical coordinates in the range θ in $[0, \pi]$ and z in $[-1, 1]$?

3. Convert the following points from spherical coordinates (ρ, ϕ, θ) to Cartesian coordinates:

- a. $(3, \pi/3, \pi)$ b. $(7, \pi/2, \pi/4)$
c. $(-1, -\pi/2, 7\pi)$ d. $(5, 0, 0)$

4. What section of the unit sphere corresponds to spherical coordinates in the range ϕ in $[0, \pi]$ and θ in $[0, \pi]$?

Find the pullback of the following surfaces into cylindrical coordinates. What is a parameterization of the surface?

5. $x^2 + y^2 = 25$ 6. $x^2 + y^2 = 30$
7. $x^2 + y^2 - z^2 = 1$ 8. $x^2 - y^2 + z^2 = 9$
9. $3x + 4y = 2$ 10. $x^2 + z^2 = 11$
11. $x^2 + y^2 = z^2$ 12. $z = x^2 - y^2$

Find the pullback of the following surfaces into spherical coordinates. What is a parameterization of the surface?

13. $x^2 + y^2 + z^2 = 25$ 14. $x^2 + y^2 + z^2 = 30$
15. $x = 1$ 16. $x + y = 1$
17. $x^2 + y^2 - z^2 = 1$ 18. $x^2 - y^2 + z^2 = 9$
19. $z = 1 - 2y$ 20. $x^2 + z^2 = 11$
21. $x^2 + y^2 = z^2$ 22. $x + y = 1$
23. $x^2z + y^2z = 2xy$ 24. $z = x^2 - y^2$

Find a parameterization of the conic section formed by the intersection of $z = p + \varepsilon x$ and the right circular cone. Then sketch its graph.

25. $p = 1, \varepsilon = \frac{1}{2}$ 26. $p = 1, \varepsilon = 0$
27. $p = 2, \varepsilon = 1$ 28. $p = -1, \varepsilon = 0.1$
29. $p = 1, \varepsilon = 2$ 30. $p = 0, \varepsilon = 1$

31. Discuss the surface of revolution given by

$$\rho = \frac{\phi}{\pi} + 1, \quad \phi \text{ in } [0, \pi]$$

What is its parameterization? Is it a deformation of the sphere?

32. Discuss the surface of revolution given by

$$\rho = 2 \sin(\phi), \quad \phi \text{ in } [0, \pi]$$

What is its parameterization? Is it a deformation of the sphere?

33. The curve formed by the intersection of a sphere centered at the origin and a plane through the origin is called a *great circle*. Let's use spherical coordinates to develop a method for parameterizing a great circle.

1. (a) A non-vertical plane through the origin is of the form $z = ax + by$, where a and b are constants. Show that spherical coordinates transforms the equation into

$$\cos(\phi) = \sin(\phi) [a \cos(\theta) + b \sin(\theta)]$$

- (b) Show that intersection of the plane with a sphere of radius R results in the parameterization

$$\mathbf{r}(t) = R \sin(\phi) \langle \cos(\theta), \sin(\theta), a \cos(\theta) + b \sin(\theta) \rangle$$

where $\tan(\phi) = a \cos(\theta) + b \sin(\theta)$. Then use a right triangle to find $\sin(\phi)$ in terms of $a \cos(\theta) + b \sin(\theta)$ to finish the parameterization.

34. Show that cylindrical coordinates results in the same parameterization for a great circle (see exercise 33) as does spherical coordinates.

35. If a point has a location of (ρ, ϕ, θ) in spherical coordinates, then its longitude is θ and its latitude is

$$\varphi = \frac{\pi}{2} - \phi$$

What is the parameterization of a sphere of radius R in latitude-longitude coordinates? (be sure to simplify expressions like

$$\sin\left(\frac{\pi}{2} - \varphi\right) \quad \text{and} \quad \cos\left(\frac{\pi}{2} - \varphi\right)$$

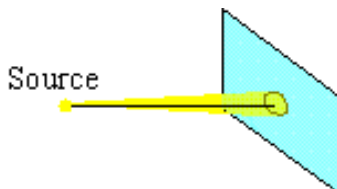
36. What is the equation in spherical coordinates of the sphere of radius R centered at $(0, 0, R)$? What is its parameterization?

37. For A , ω , k , and δ constants, the function

$$f(\rho, t) = \frac{A}{\rho} \cos(\omega t - k\rho + \delta)$$

is a *spherical wave* about the origin with angular frequency ω , wavenumber k , and phase δ . Explain why the spherical wave is the same in all directions. What happens to the spherical wave as the spherical distance ρ goes to infinity?

38. (Continues 37) Spherical waves are often studied as they impact a small region of a plane.



In particular, for $R > 0$ constant, points (x, y, R) in the plane $z = R$ are at a distance ρ from the origin, where

$$\rho = (r^2 + R^2)^{1/2}$$

and $r^2 = x^2 + y^2$. Show that the Maclaurin's series of ρ as a function of r is of the form

$$\rho = R + \frac{r^2}{2R} - \frac{r^4}{8R^3} + \frac{r^6}{16R^5} + \dots$$

so that if $r^2 \ll R$ (i.e., if r^2 is much, much, less than R , corresponding to the region of impact in the $z = R$ plane being relatively small with respect to the distance from the source), then

$$\rho \approx R + \frac{r^2}{2R}$$

Finally, explain why for small regions in the $z = R$ plane, a spherical wave about the origin is approximately the same as

$$f(r, t) = \frac{A}{R} \cos\left(\omega t - \frac{kr^2}{2R} + \delta_1\right)$$

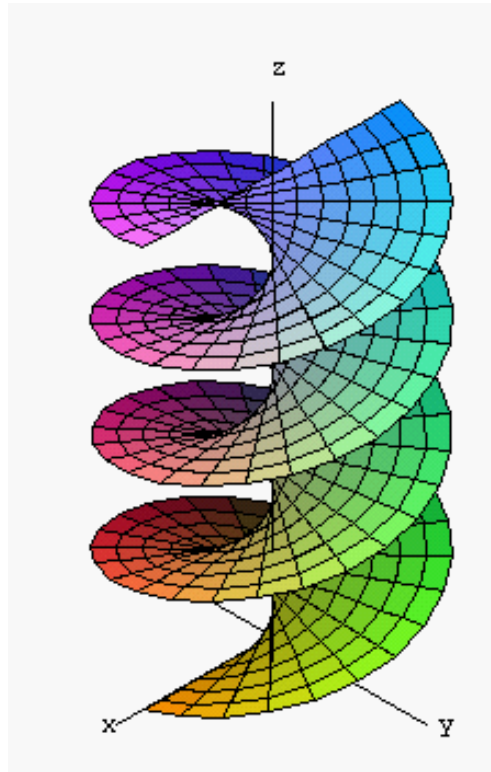
where $\delta_1 = \delta - kR$ is a new phase constant for the spherical wave. (i.e., a change in phase).

39. The interconnected double helix structure of DNA describes a *helicoid*, which is the surface parametrized by

$$\mathbf{r}(\theta, v) = \langle v \cos(\theta), v \sin(\theta), \theta \rangle$$

Show that $v = \theta \tan(\phi)$ and that the helicoid in spherical coordinates is given

by $\rho = \theta \sec(\phi)$.



40. What is the parameterization of the helicoid in exercise 39 in cylindrical coordinates?

41. Write to Learn: Explain in a short essay why a torus is radially symmetric but why there *does not exist* a positive continuous function $f(\phi)$ on $[0, \pi]$ such that the torus is given by $\rho = f(\phi)$ for ϕ in $[0, \pi]$ in spherical coordinates. (i.e., explain why it is impossible to deform a sphere into a torus).

42. Is an ellipsoid a radially symmetric deformation of the sphere? What about a paraboloid? Or a hyperboloid? Explain.

Cylindrical and spherical coordinates are examples of curvilinear coordinate systems. Exercises 43-46 explore some additional curvilinear coordinates.

43. Ellcylindrical coordinates assign a point P in three dimensional space the coordinates (u, θ, z) , where

$$x = \cosh(u) \cos(\theta), \quad y = \sinh(u) \sin(\theta)$$

and where z is the usual z -coordinate. What surface corresponds to $u = a$ for a constant? What surface corresponds to $\theta = c$ for c constant?

44. Paraboloidal coordinates assign a point P in three dimensional space the coordinates (u, v, θ) , where

$$x = uv \cos(\theta), \quad y = uv \sin(\theta), \quad z = \frac{u^2 - v^2}{2}$$

What surface corresponds to $u = a$ for a constant? What surface corresponds to $v = b$ for b constant? What surface corresponds to $\theta = c$ for c constant?

45. Bispherical coordinates assign a point P in three dimensional space the coordinates (v, ϕ, θ) , where

$$x = \frac{\sin(\phi) \cos(\theta)}{\cosh(v) - \cos(\phi)}, \quad y = \frac{\sin(\phi) \sin(\theta)}{\cosh(v) - \cos(\phi)}, \quad z = \frac{\sinh(v)}{\cosh(v) - \cos(\phi)}$$

Explain a surface of the form $v = k$ for k constant is a sphere of radius $\operatorname{csch}(k)$ centered at $(0, 0, \operatorname{coth}(k))$.

46. Toroidal coordinates assign a point P in three dimensional space the coordinates (v, ϕ, θ) , where

$$x = \frac{\sinh(v) \cos(\theta)}{\cosh(v) - \cos(\phi)}, \quad y = \frac{\sinh(v) \sin(\theta)}{\cosh(v) - \cos(\phi)}, \quad z = \frac{\sin(\phi)}{\cosh(v) - \cos(\phi)}$$

Explain a surface of the form $v = k$ for k constant is a *torus*, and explain why if $k_1 \neq k_2$, then $v = k_1$ does not intersect $v = k_2$.